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PHYS 2125.104.603

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**Lab 2: Vectors**

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Lab 2: Vectors

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Lab Section: #603

September 22, 2015

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2.) Data:

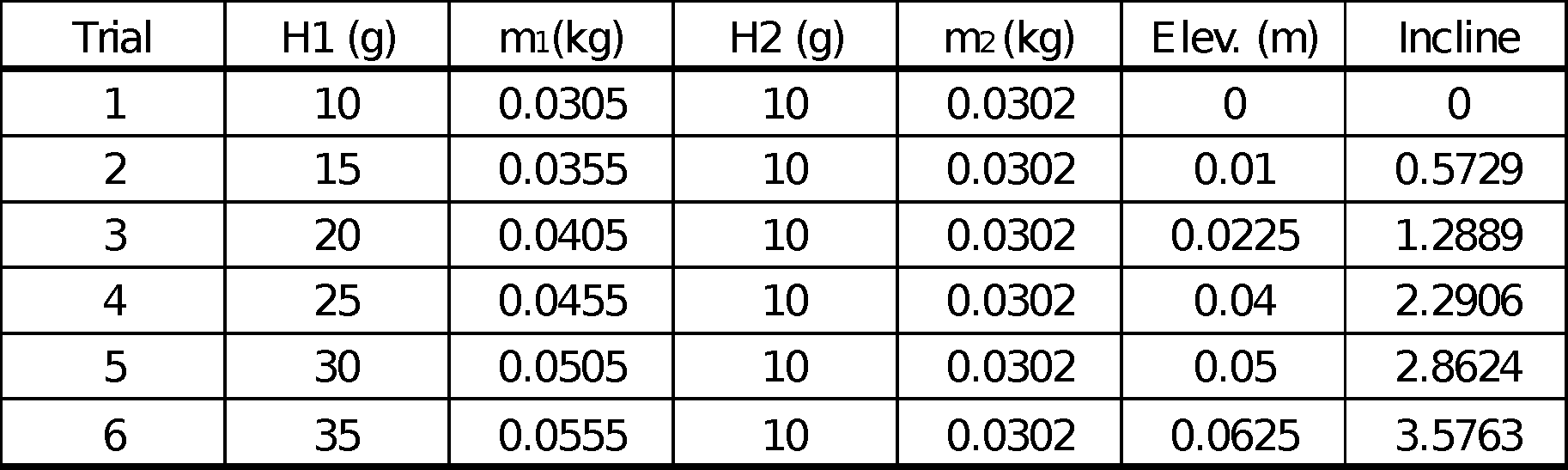


Table 2: Data table for air track measurements.

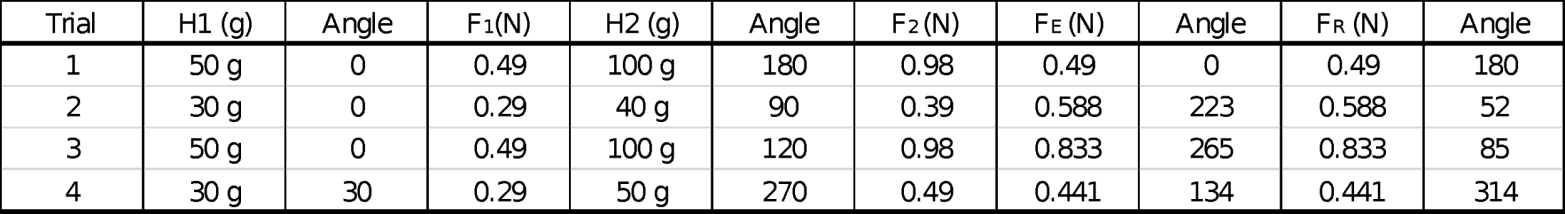


Table 3: Data table for force table measurements.

3.) Calculations:

Sample calculations from:

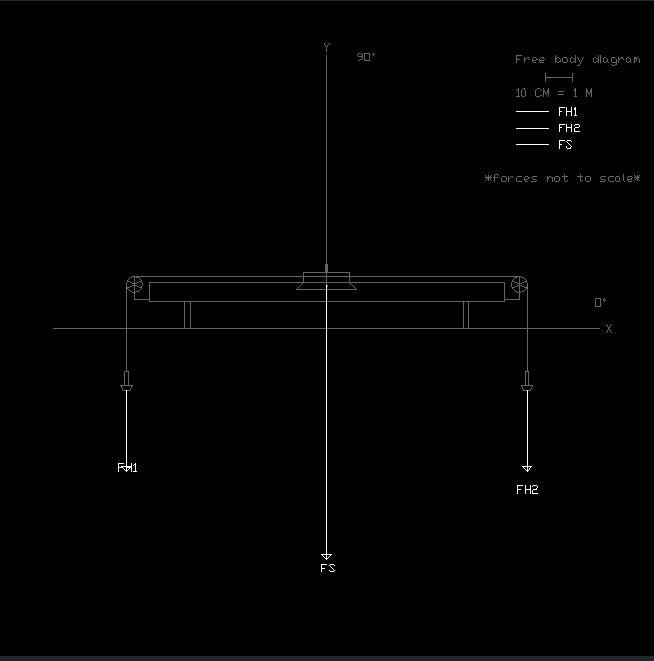
Free body diagram trial 3

*A*=

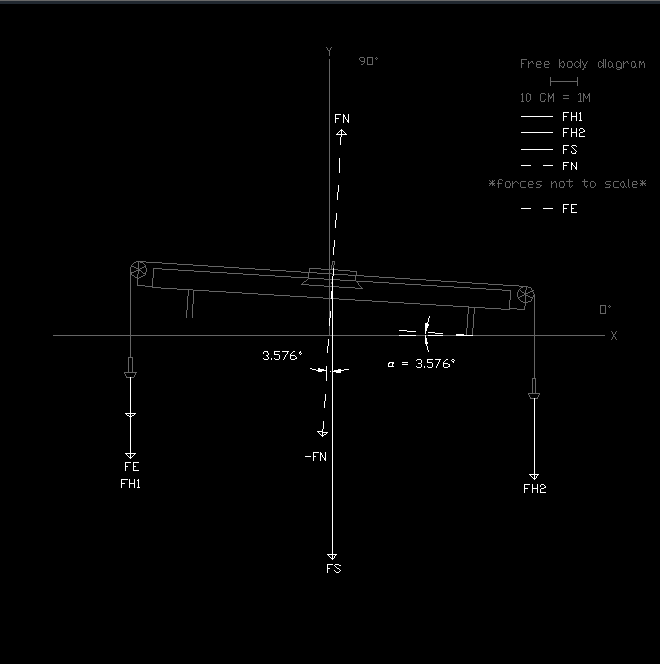
4.) Analysis:

**(Q6.0.3)**

1. As m1 increases in table 2, the elevation and incline angle increases to compensate for the change in mass



Free Body Diagram 1: Flat Track.

1. 

Free Body Diagram 2: Inclined Track.

1. alpha shown above
2. The angle between the negative normal force and weight on track is alpha

|  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| **Trial** | **mass M1** | **Mass M2** | **Force M1** | **Force M2** | **Angle** | **M1** | | **M2** | |
|  |  |  |  |  |  | **X** | **Y** | **X** | **Y** |
| 1 | 0.031 | 0.030 | 0.299 | 0.296 | 0.000 | 0.299 | 0.000 | 0.296 | 0.000 |
| 2 | 0.036 | 0.030 | 0.348 | 0.296 | 0.010 | 0.348 | 0.003 | 0.296 | 0.003 |
| 3 | 0.041 | 0.030 | 0.397 | 0.296 | 0.022 | 0.397 | 0.009 | 0.296 | 0.009 |
| 4 | 0.046 | 0.030 | 0.446 | 0.296 | 0.040 | 0.446 | 0.018 | 0.296 | 0.018 |
| 5 | 0.051 | 0.030 | 0.495 | 0.296 | 0.050 | 0.494 | 0.025 | 0.296 | 0.025 |
| 6 | 0.056 | 0.030 | 0.544 | 0.296 | 0.062 | 0.543 | 0.034 | 0.295 | 0.034 |
| **UNITS** | **(kg)** | | **(N)** | | **(°)** | **(N)** | | **(N)** | |

Table 4: X and Y components and Resultant of weight on glider.

\*F(r) = resultant force, F(n) = magnitude of the Normal Force

\*You’ll also notice how the magnitude of M1 equivocates to M2 plus the normal force implying that there is only a negligible amount of force acting within the system.

**(||M1||) ≈ (||M2|| + F(n))**

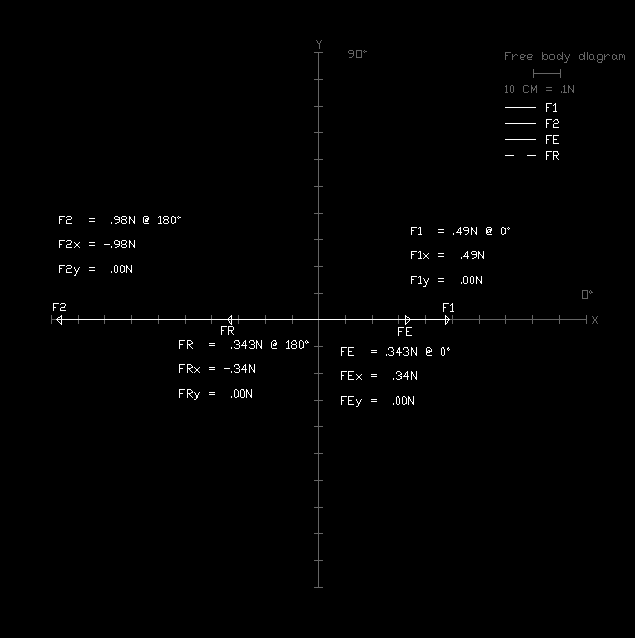
|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **F(n)** | **||M1||** | **||M2||** | **||M2||+Fn** | **F(r )** |
|  |  |  |  |  |
| 0.000 | 0.299 | 0.296 | 0.296 | 0.003 |
| 0.037 | 0.348 | 0.296 | 0.333 | 0.015 |
| 0.083 | 0.397 | 0.296 | 0.379 | 0.017 |
| 0.148 | 0.446 | 0.296 | 0.445 | 0.001 |
| 0.185 | 0.495 | 0.297 | 0.482 | 0.013 |
| 0.232 | 0.544 | 0.297 | 0.529 | 0.015 |
| **(N)** | | **(N)** | | **(N)** |

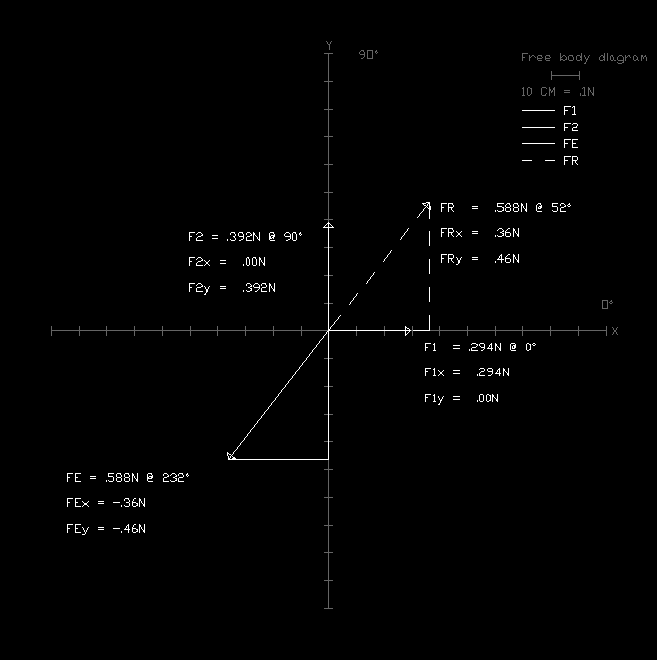
4.) Analysis:

**(Q6.0.4)**

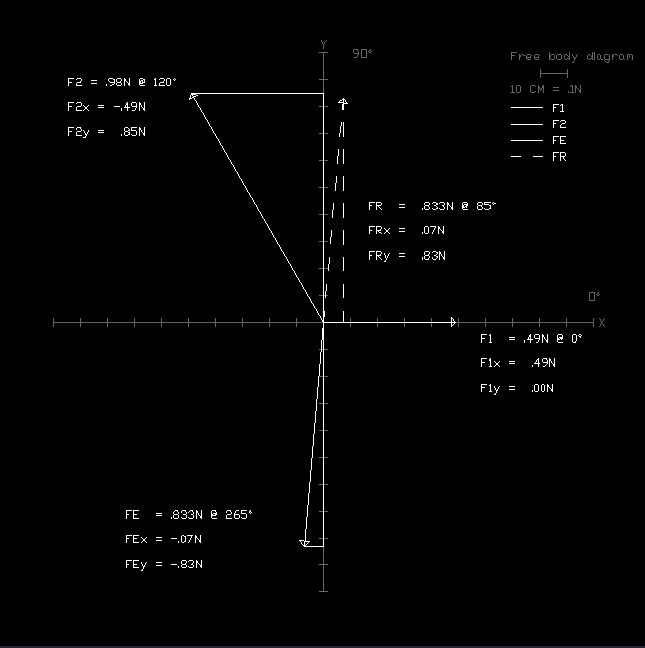
1. Free Body Diagrams (shown in each Diagram below)
2. X & Y Axes Labels (shown in each Diagram below)
3. X & Y vector forces components (shown in each Diagram below)

Free Body Diagram 3: Trial 1.

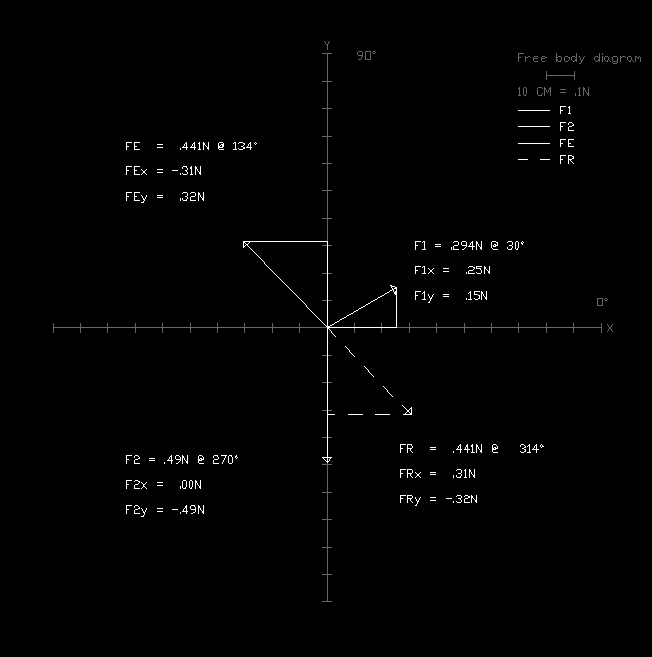




Free Body Diagram 4: Trial 2.



Free Body Diagram 5: Trial 3.

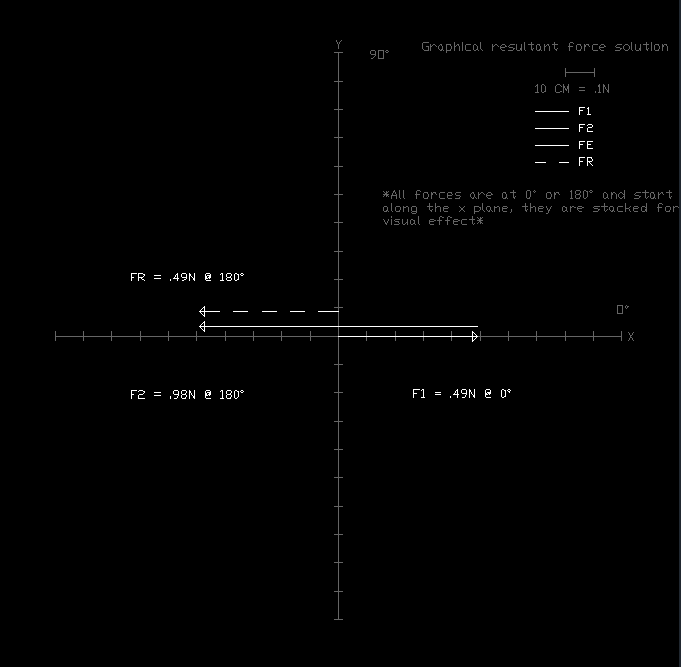


Free Body Diagram 6: Trial 4.

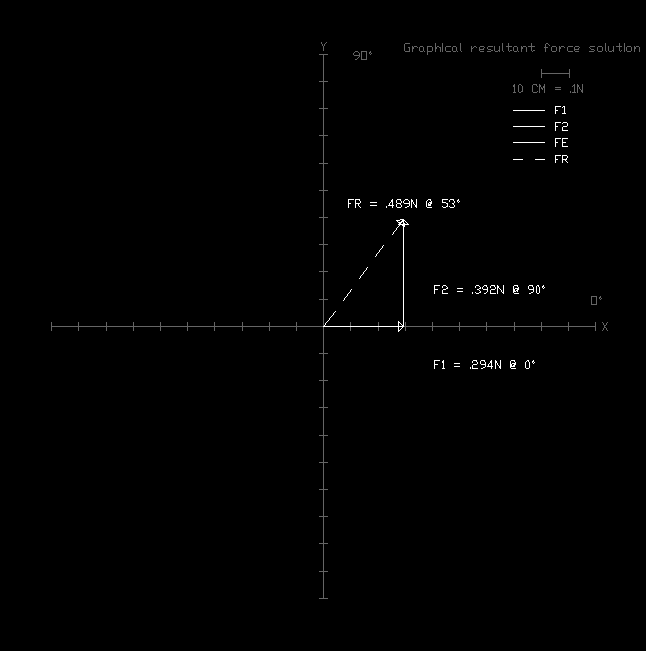
4.) Analysis:

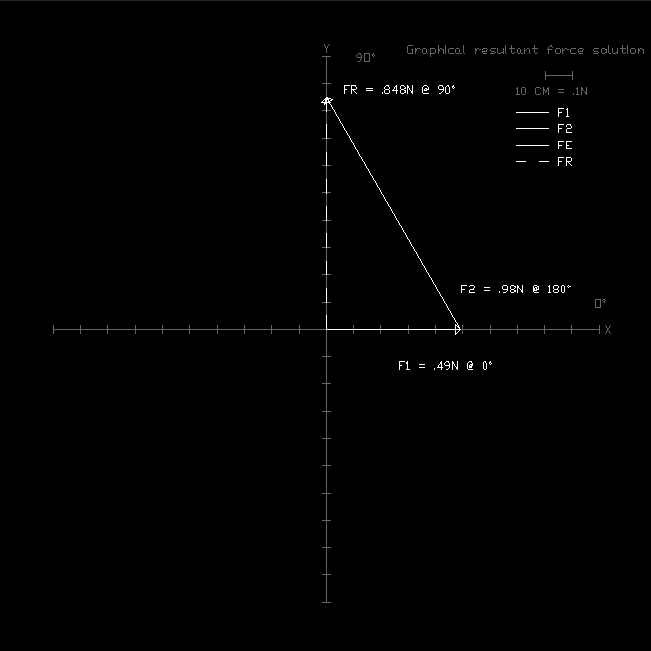
**(Q6.0.4)**

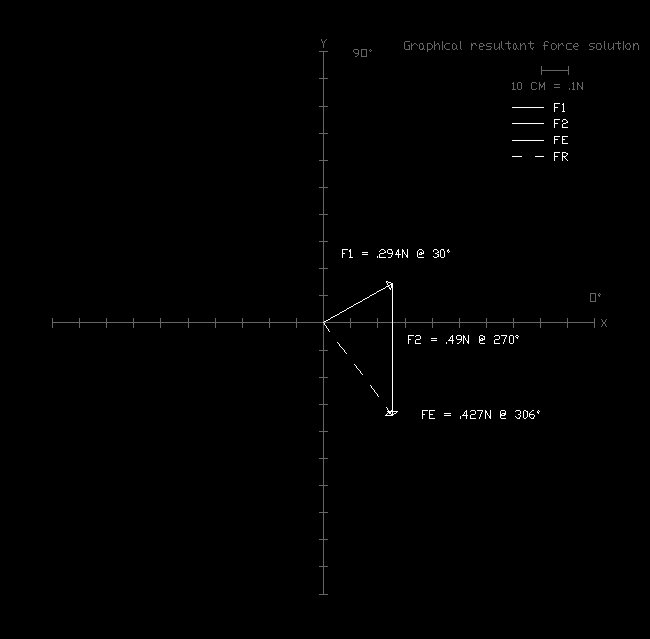
1. Graphical Solutions



Graphical Solution 1: Trial 1.

Graphical Solution 2: Trial 2.

Graphical Solution 3: Trial 3.

Graphical Solution 4: Trial 4.

1. Component addition

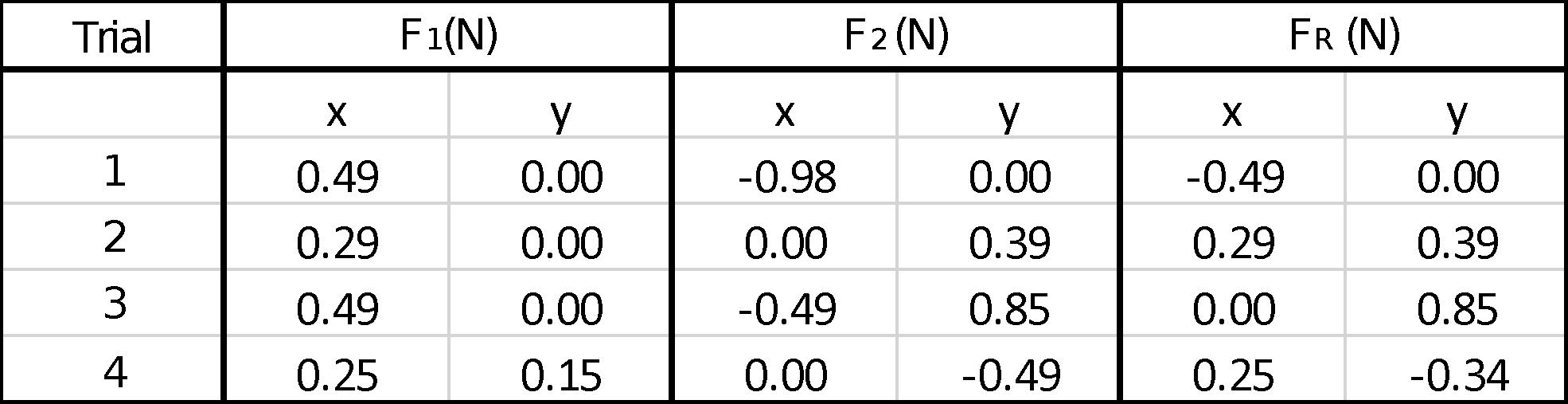


Table 5: Component Addition.

**(Q6.0.5)**

1. Quantities
   1. Scalar: distance (), mass ()
   2. Vector: Acceleration (9.8 ), Velocity (
2. Labeled axes for the diagrams, they coincide with the table
3. We resolved the vectors in the following table
   1. Resultant Vector

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| **A** | | **B** | | **Resultant vector** | | **||Resultant||** | **Resultant** |
| **X** | **Y** | **X** | **Y** | **X** | **Y** | **Vector** | **Angle** |
| -18.7938 | -6.8404 | 6.8404 | -18.7938 | -11.953 | -25.643 | 28.284 | 245° |

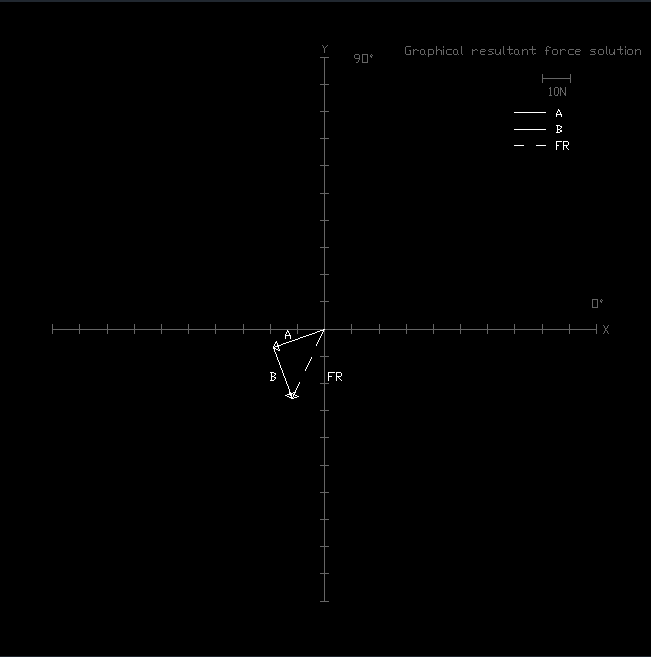
|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| **C** | | **D** | | **Resultant vector** | | **||Resultant||** | **Resultant** |
| **X** | **Y** | **X** | **Y** | **X** | **Y** | **Vector** | **Angle** |
| -50 | 86.6025 | 45 | 0 | -5 | 86.6025 | 86.746 | 93.299° |

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| **E** | | **F** | | **Resultant vector** | | **||Resultant||** | **Resultant** |
| **X** | **Y** | **X** | **Y** | **X** | **Y** | **Vector** | **Angle** |
| 43.301 | 25 | 100 | 0 | 142.301 | 25 | 145.4656 | 9.89605° |

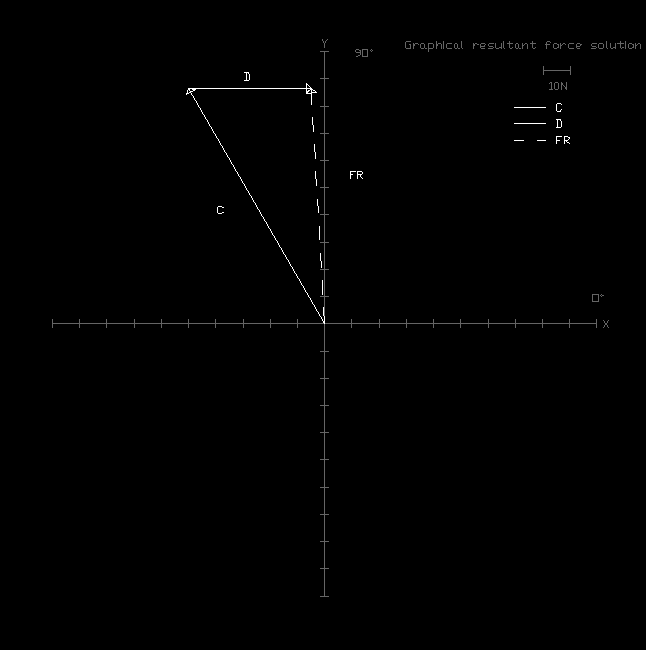
|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **G** | | **H** | | **I** | |
| **X** | **Y** | **X** | **Y** | **X** | **Y** |
| -25.9807 | -15 | 10 | 0 | -10 | 17.3205 |

|  |  |  |  |
| --- | --- | --- | --- |
| **Resultant vector** | | **||Resultant||** | **Resultant** |
| **X** | **Y** | **Vector** | **Angle** |
| -25.981 | 2.3205 | 26.0844 | 174.896159 |

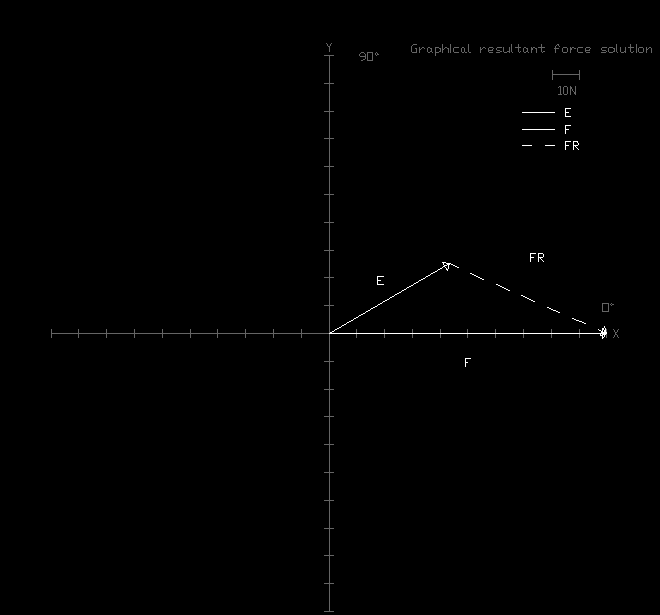
* 1. Graphically



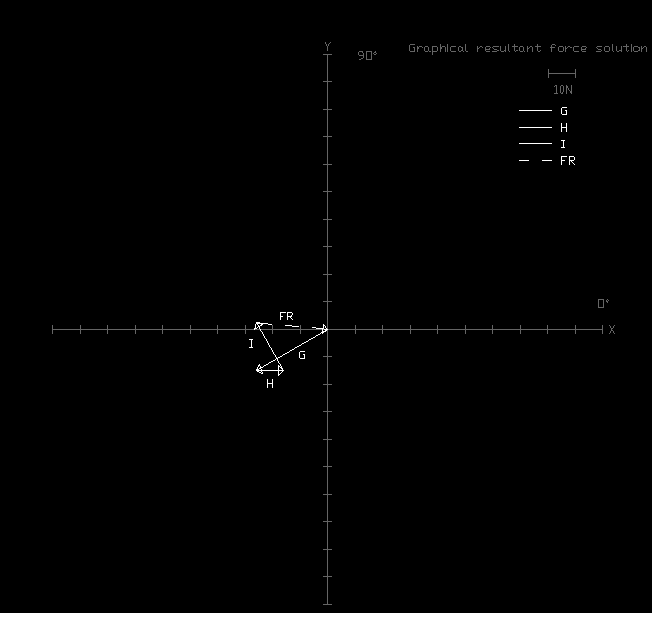
Graphical Solution 5.



Graphical Solution 6.



Graphical Solution 7.



Graphical Solution 8.